

# A Lightweight Finite State Machine C++ Library aimed at Seamless Integration with Robotic Middlewares

*David Estévez, Juan G. Victores, Carlos Balaguer*

*destevez@ing.uc3m.es*

*Robotics Lab research Group  
Universidad Carlos III de Madrid*

# Outline

1. Introduction
2. Robot Devastation
3. StateMachineLib
4. Conclusions

# Introduction

Robots are used nowadays in different areas:

- Industry, manufacturing
- Transportation
- Assistive technologies
- Military applications

# Introduction

But robots can be also used for  
**entertainment...**

# Introduction

Augmented Reality (AR) games can be enhanced with robots.

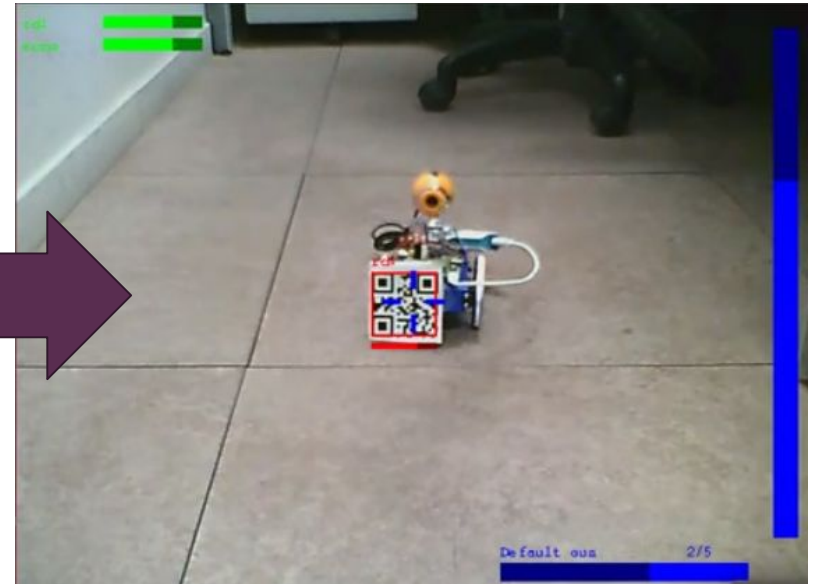
Limitations:

- Real world avatars -> real world issues (noise, latency, etc).
- Ambitious vs feasible

# ROBOT DEVASTATION



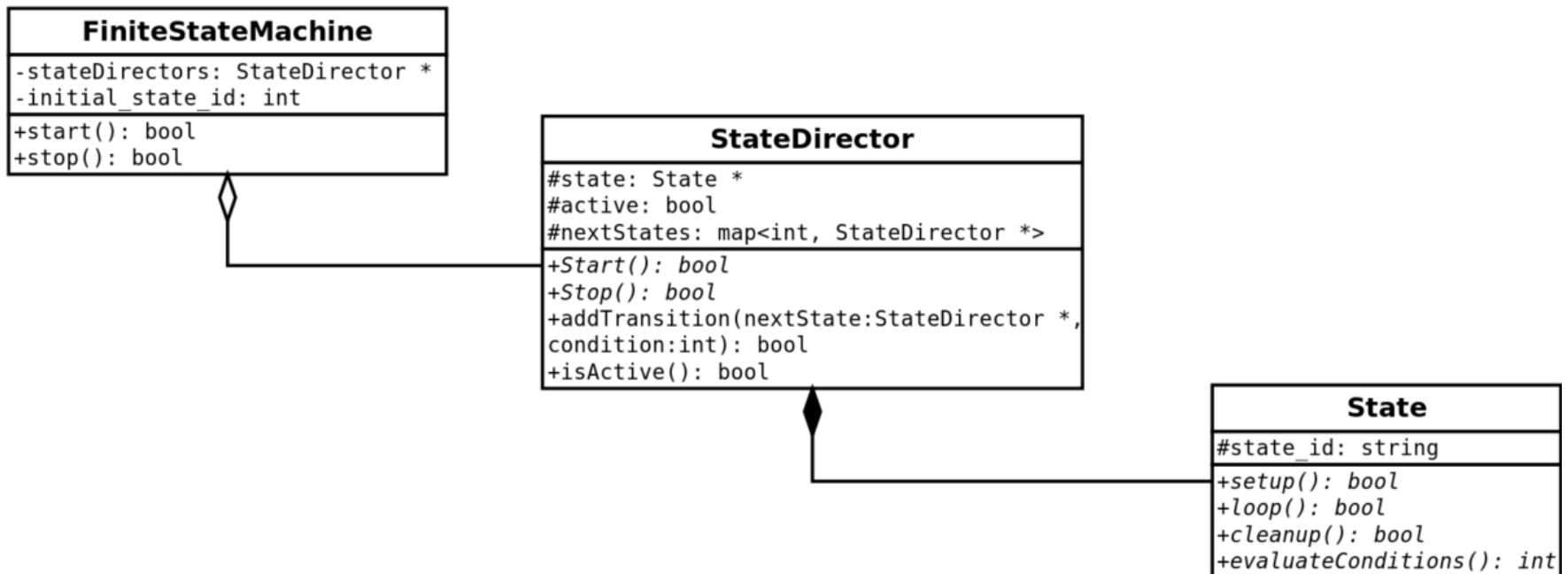
**Real Robot Combat**



**Robot Devastation** (Estevez, Victores, Morante & Balaguer, 2015)

# StateMachineLib

rd::StateMachineLib main classes



# StateMachineLib

**State:** base class for each FSM state.

- `setup()`
- `loop()`
- `cleanup()`
- `evaluateConditions()`



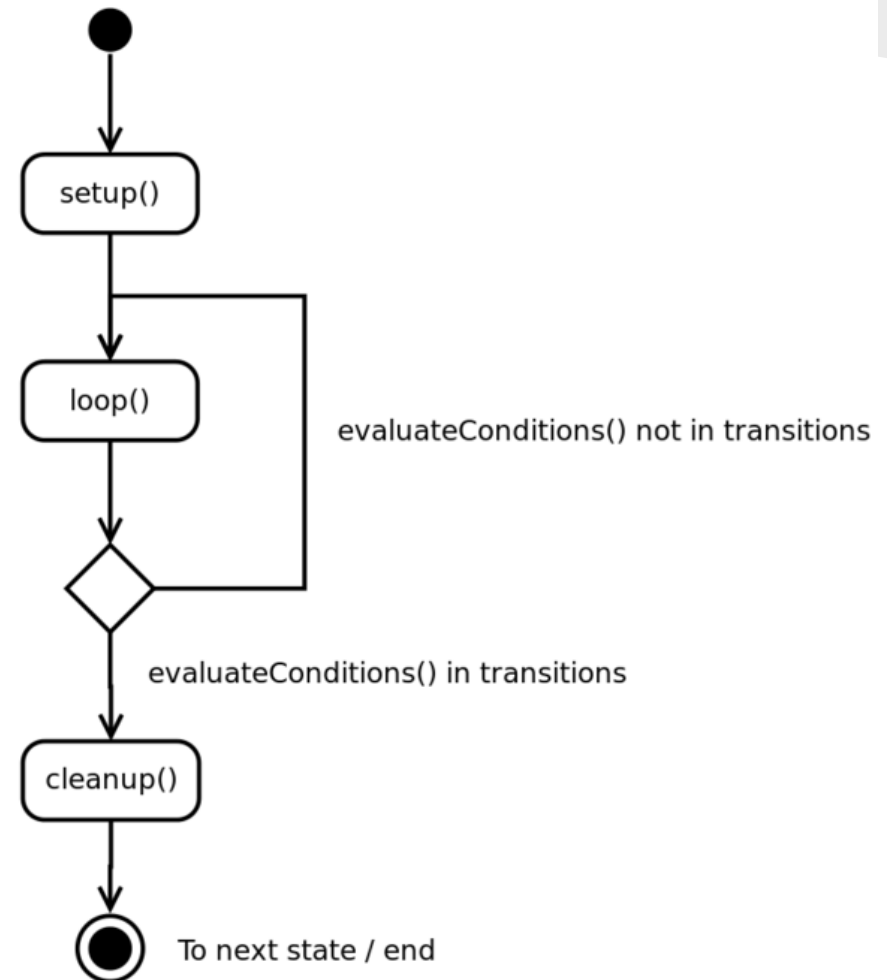
# StateMachineLib

## StateDirector:

Controls FSM flow

- Different possible implementations:  
YARP, C++11,  
pthread, etc

From previous state



# StateMachineLib

**FiniteStateMachine:** wraps the states with a nice interface to manipulate the FSM

- **StateMachineBuilder** class is provided to encapsulate the creation of a FSM from the State objects.

# Conclusions

## Robot Devastation game FSM Implementation

4 states:

- **Init:** game initialization and server logging
- **Game:** game main screen and gameplay
- **Dead:** dead screen and wait for respawn
- **Exit:** server logout and game cleanup

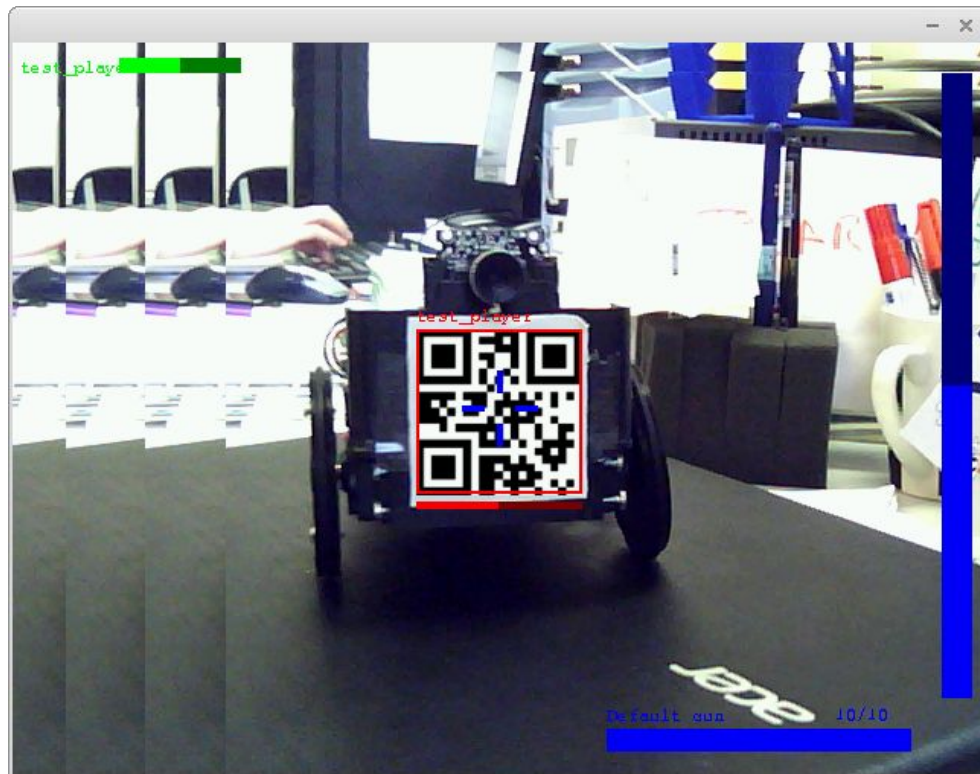
# Conclusions

**Init:** game initialization and server logging



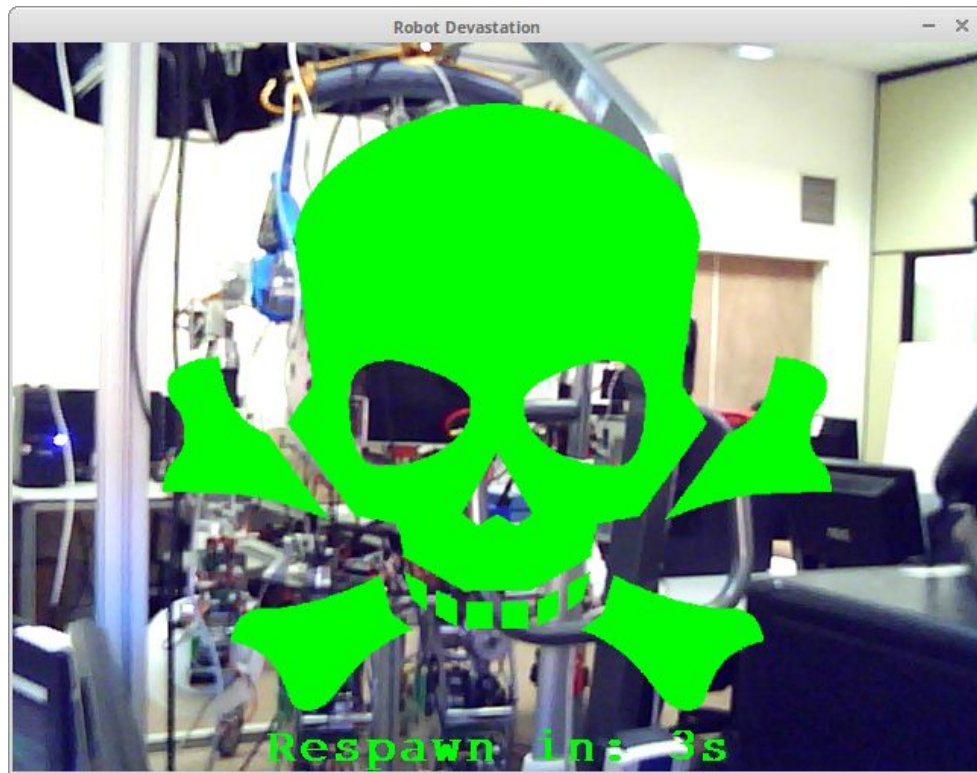
# Conclusions

**Game:** game main screen and gameplay



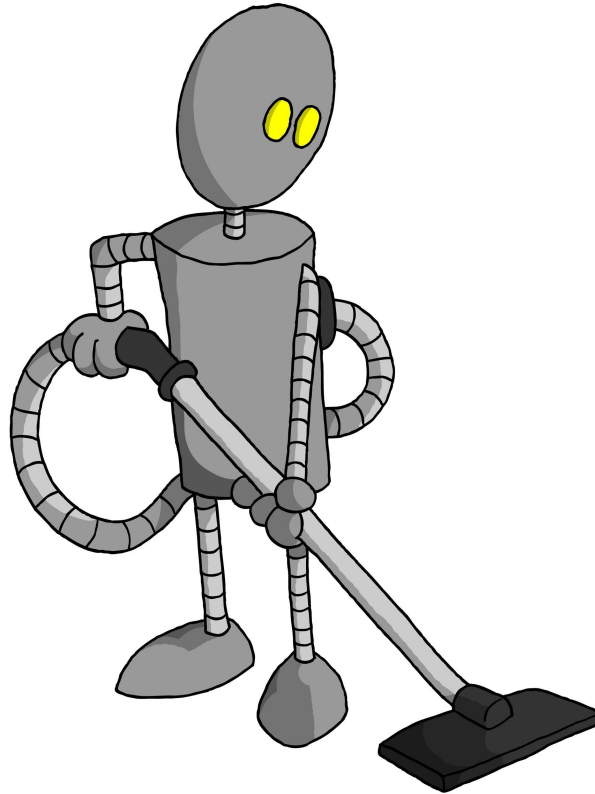
# Conclusions

**Dead:** dead screen and wait for respawn



# Conclusions

**Exit:** server logout and game cleanup



src: <https://wemovechicago.com/moving-cleaning-checklist/>

# Join us!

- Source code available at:  
<https://github.com/asrob-uc3m/robotDevastation>
- Check out our Wiki too:  
[http://asrob.uc3m.es/index.php/Robot\\_Devastation](http://asrob.uc3m.es/index.php/Robot_Devastation)





# A Lightweight Finite State Machine C++ Library aimed at Seamless Integration with Robotic Middlewares

## Thank you!

*David Estevez, Juan G. Victores, Carlos  
Balaguer*